## Simple Heteroclinic Orbit Examples in the Plane

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July 4, 2012
9th AIMS Conference on Dynamical Systems, Differential Equations and Applications Special Session 10

## Outline

- Planar Systems
- Heteroclinic Orbits
- First ode, spirals, every point on a heteroclinic orbit
- Second ode, heteroclinic limit points along a line
- Power Series Method for odes


## Planar Systems

$\dot{x}=P(x, y), \dot{y}=Q(x, y)$ for real polynomials $P(x, y), Q(x, y)$ in $x$ and $y$ form a polynomial differential system in the plane, and have been extensively studied over the decades.

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Hilbert's 16th problem: how many limit cycles when bounding the polynomial order.

Over a thousand papers on quadratic systems alone, with a bibliography compiled by the Delft University of Technology (1904-1997)

## Heteroclinic Orbits

A heteroclinic orbit is a solution to the system of odes $\dot{x}=f(t, x)$ where $x \rightarrow x_{a}$ as $t \rightarrow \infty$ and $x \rightarrow x_{b}$ as $t \rightarrow-\infty$ for given points $x_{a}, x_{b}$.

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Heteroclinic orbits typically occur when a system can cycle between different states, spending substantial time near each one.
They often separate the solution space into regions with qualitatively different behavior.

Numerically locating heteroclinic orbits (if they exist) is challenging, and often reduces to solving an infinite boundary value problem.

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## First ODE

Consider the system

$$
\begin{aligned}
& \dot{x}=a\left(x^{2}-y^{2}\right)-2 b x y+c x-d y+e, \\
& \dot{y}=b\left(x^{2}-y^{2}\right)+2 a x y+d x+c y+f, \\
& \text { with } \\
& x(0)=g, \\
& y(0)=h \text {, }
\end{aligned}
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for given constants $a$ to $h$.

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With $z(t)=x(t)+i y(t)$,

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\dot{z}=(a+i b) z^{2}+(c+i d) z+(e+i f) \quad \text { with } \quad z(0)=g+i h,
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with all constants $a$ to $h$ being real.

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with all constants $a$ to $h$ being real.
By completing the square and scaling by $a+i b$, any quadratic complex ode can be reduced to

$$
\dot{z}=z^{2}+(a+i b) \quad \text { with } \quad z(0)=c+i d
$$

where $a, b, c$ and $d$ are real constants.

## Analytic Solution

$$
\begin{aligned}
& \text { Let } e=\frac{\sqrt{a+\sqrt{a^{2}+b^{2}}}}{\sqrt{2}} \text { and } f=\frac{b}{\sqrt{2\left(a+\sqrt{a^{2}+b^{2}}\right)}} \text { so } \\
& \sqrt{a+i b}= \pm(e+i f) \text { and } \sqrt{-(a+i b)}= \pm(-f+i e) .
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& z=(e+i f) \tan ((e+i f) t+C), C=\arctan \left(\frac{c+i d}{e+i f}\right)=g+i h .
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Using the definitions of complex arctan, log, sin and cos, we get

$$
\begin{array}{r}
z(t)=\quad \frac{e \sin (2(e t+g))-f \sinh (2(f t+h))}{\cosh (2(f t+h))+\cos (2(e t+g))} \\
+i \frac{f \sin (2(e t+g))+e \sinh (2(f t+h))}{\cosh (2(f t+h))+\cos (2(e t+g))}
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Then $z(t)=x(t)+i y(t)=\frac{-\left(t+\frac{c}{c^{2}+d^{2}}\right)-i \frac{d}{c^{2}+d^{2}}}{\left(t+\frac{c}{c^{2}+d^{2}}\right)^{2}+\left(\frac{d}{c^{2}+d^{2}}\right)^{2}}$.

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If we let $m=c /\left(c^{2}+d^{2}\right)$ and $n=d /\left(c^{2}+d^{2}\right)$ then
$x(t)=-\frac{t+m}{(t+m)^{2}+n^{2}}$ and $y(t)=-\frac{n}{(t+m)^{2}+n^{2}}$.

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$x(t)=-\frac{t+m}{(t+m)^{2}+n^{2}}$ and $y(t)=-\frac{n}{(t+m)^{2}+n^{2}}$.
$(x(t), y(t)) \rightarrow(0,0)$ as $t \rightarrow \pm \infty$, so the solution starting from any point is on a homoclinic orbit, with the same homoclinic point.

## Zero Constant Orbits

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\begin{aligned}
& x^{2}+y^{2}=\frac{(t+m)^{2}+n^{2}}{\left((t+m)^{2}+n^{2}\right)^{2}}= \\
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All homoclinic orbits are circles, center and radius $1 /(2 n)$.


## Positive Real Constant

If $b=0$ and $a>0$, then $e=\sqrt{a}, f=0$ and

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z(t)=x(t)+i y(t)=\sqrt{a} \cdot \frac{\sin (2(\sqrt{a} t+g))+i \sinh (2 h)}{\cosh (2 h)+\cos (2(\sqrt{a} t+g))} .
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Orbits are circles $x^{2}+(y-m)^{2}=m^{2}-a$ where $m=a \operatorname{coth}(2 h)$, all of which are periodic, so no heteroclinic orbits.

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Velocity small near the origin, can become very large away from the origin.

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so the period is the same on each circular orbit.
Velocity small near the origin, can become very large away from the origin. $\dot{z}=z^{2}+1, z(0)=0.05+0.05 i$ :


## Negative Real Constant

If $b=0$ and $a<0$, then $\pm(e+i f)=\sqrt{a}=i \sqrt{-a}$, so $e=0$ and $f=\sqrt{-a}$, and

$$
z(t)=x(t)=i y(t)=\sqrt{-a} \cdot \frac{-\sinh (2(\sqrt{-a} t+h))+i \sin (2 g)}{\cosh (2(\sqrt{-a} t+h))+\cos (2 g)} .
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Orbits cannot be represented as algebraic equations in $x$ and $y$ only, and are spirals similar to Carnu or Euler spirals, with exponential convergence for large magnitude $t$.

## First Example

$$
\dot{z}=z^{2}+(1+i), z(0)=-1,-0.8, \ldots, 1
$$




## First Example, More Dramatic

$\dot{z}=z^{2}+(1+i), z(0)=-2$.




## First Example, More Dramatic

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Same exponential convergence after more dramatic intermediate circular curve.

## Second Example

$$
\dot{z}=z^{2}+1+i / 2, \text { with } z(0)=0,0.1,0.2,0.3 .
$$




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$$




The smaller the ratio $a / b$, the faster the convergence of the spiral.

## Second ODE

Consider $\dot{x}=-y(1-a x-b y)$ and $\dot{y}=x(1-a x-b y)$ with $x(0)=c, y(0)=d$.

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If $r<1 /\left(a^{2}+b^{2}\right)$, orbits will be periodic. Otherwise, orbits are heteroclinic on arcs of circles, with endpoints on the line $1-a x-b y=0$.

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If $r<1 /\left(a^{2}+b^{2}\right)$, orbits will be periodic. Otherwise, orbits are heteroclinic on arcs of circles, with endpoints on the line $1-a x-b y=0$.

The line $-a x-b y=0$ could be called a heteroclinic line.

## Analytic Solution

Starting with $\dot{x}=-y(1-a x-b y)$ and $\dot{y}=x(1-a x-b y)$ with $x(0)=c, y(0)=d$, let $r=\sqrt{c^{2}+d^{2}}, x(t)=r \cos (\theta(t))$ and $y(t)=r \sin (\theta(t))$.

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$$
\theta(t)=-2 \arctan \left(\frac{-b r+\tanh \left(\frac{t+C}{2} \sqrt{r^{2}\left(a^{2}+b^{2}\right)-1}\right) \sqrt{r^{2}\left(a^{2}+b^{2}\right)-1}}{1+a r}\right)
$$

when $r^{2}>1 /\left(a^{2}+b^{2}\right)$, and
$\theta(t)=-2 \arctan \left(\frac{-b r-\tan \left(\frac{t+C}{2} \sqrt{1-r^{2}\left(a^{2}+b^{2}\right)}\right) \sqrt{1-r^{2}\left(a^{2}+b^{2}\right)}}{1+a r}\right)+2 k \pi$
when $r^{2}<1 /\left(a^{2}+b^{2}\right)$, and $k$ is an integer chosen to ensure $\theta(t)$ stays continuous and monotonic.

## Example

$\dot{x}=-y(1-x-y)$ and $\dot{y}=x(1-x-y)$ with $d=0$ and $c=0.05,0.1,0.15, \ldots, 2$ :


## More General Case

$\dot{x}=-y f(x, y), \dot{y}=x f(x, y)$ for any function $f(x, y)$ has arcs of circles as orbits, with the solutions of $f(x, y)=0$ as heteroclinic lines.

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For example, $x^{\prime}=-y\left(y-x^{2}\right)$ and $y^{\prime}=x\left(y-x^{2}\right)$ with $x(0)=0$ and $y(0)=-0.1,-0,2,-0.3, \ldots,-6$.


## Power Series Method

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BUT if the RHS of the ode is polynomial in the dependent variables, we can write out $y$ as a power series in $t$, substitute, and explicitly find the coefficients - the Power Series Method. Usually only seen when solving linear second order odes with non constant coefficients (Frobenius around regular singular points).

## Power Series Method

Taylor methods to solve $\dot{y}=f(t, y)$ writes $y(t+h)$ as a Taylor series around $y(t)$, substituting successive derivatives of $f$. Runge-Kutta and related methods replace derivatives by additional function evaluations and have the same accuracy.

BUT if the RHS of the ode is polynomial in the dependent variables, we can write out $y$ as a power series in $t$, substitute, and explicitly find the coefficients - the Power Series Method. Usually only seen when solving linear second order odes with non constant coefficients (Frobenius around regular singular points). The PSM can be used to approximate a system of first order initial value polynomial odes to arbitrary order.

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- No transcendental function evaluation, so is much faster.


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$\dot{u}_{1}=u_{2}, u_{1}(0)=a ; \dot{u}_{2}=(\cos y) \dot{y}=u_{3} u_{2}, u_{2}(0)=\sin (a)$;
$\dot{u}_{3}=(-\sin y) \dot{y}=-u_{2}^{2}, u_{3}(0)=\cos (a)$.

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