Simple Heteroclinic Orbit Examples in the Plane

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July 4, 2012 9th AIMS Conference on Dynamical Systems, Differential Equations and Applications Special Session 10

Background	First ODE	Second ODE	PSM
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• Planar Systems

Jutline

- Heteroclinic Orbits
- First ode, spirals, every point on a heteroclinic orbit
- Second ode, heteroclinic limit points along a line
- Power Series Method for odes



Background	First ODE	Second ODE	PSM
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Planar Systems			

 $\dot{x} = P(x, y), \ \dot{y} = Q(x, y)$ for real polynomials $P(x, y), \ Q(x, y)$ in x and y form a polynomial differential system in the plane, and have been extensively studied over the decades.



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Hilbert's 16th problem: how many limit cycles when bounding the polynomial order.



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Hilbert's 16th problem: how many limit cycles when bounding the polynomial order.

Over a thousand papers on quadratic systems alone, with a bibliography compiled by the Delft University of Technology (1904-1997)



Background	First ODE	Second ODE	PSM
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Heteroclinic Orbits	5		



Background	First ODE	Second ODE	PSM
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Heteroclinic Orbits	;		

A homoclinic orbit is the special case $x_a = x_b$.



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Heteroclinic orbits typically occur when a system can cycle between different states, spending substantial time near each one. They often separate the solution space into regions with qualitatively different behavior.



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Numerically locating heteroclinic orbits (if they exist) is challenging, and often reduces to solving an infinite boundary value problem.



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Heteroclinic Examples					

Very simple examples include the simple pendulum with orbits joining the unstable equilibria,



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Simple Heteroclinic Orbit Examples in the Plane

Background	First ODE	Second ODE	PSM
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First ODE			

Consider the system

$$\dot{x} = a(x^2 - y^2) - 2bxy + cx - dy + e,$$

 $\dot{y} = b(x^2 - y^2) + 2axy + dx + cy + f,$ with $x(0) = g,$
 $y(0) = h,$

for given constants a to h.



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With
$$z(t) = x(t) + iy(t)$$
,
 $\dot{z} = (a + ib)z^2 + (c + id)z + (e + if)$ with $z(0) = g + ih$,

with all constants a to h being real.



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with all constants a to h being real.

By completing the square and scaling by a + ib, any quadratic complex ode can be reduced to

$$\dot{z} = z^2 + (a + ib)$$
 with $z(0) = c + id$,

where a, b, c and d are real constants.



Background	First ODE	Second ODE	PSM
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Analytic Solution

Let
$$e = \frac{\sqrt{a + \sqrt{a^2 + b^2}}}{\sqrt{2}}$$
 and $f = \frac{b}{\sqrt{2(a + \sqrt{a^2 + b^2})}}$ so $\sqrt{a + ib} = \pm (e + if)$ and $\sqrt{-(a + ib)} = \pm (-f + ie)$.



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 $\sqrt{a + ib} = \pm (e + if)$ and $\sqrt{-(a + ib)} = \pm (-f + ie)$. Then
 $(c + id)$

$$z = (e + if) \operatorname{tan}((e + if)t + C), \ C = \operatorname{arctan}\left(\frac{c + ia}{e + if}\right) = g + ih.$$



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$$z = (e + if) \operatorname{tan}((e + if)t + C), \ C = \arctan\left(\frac{c + id}{e + if}\right) = g + ih.$$

Using the definitions of complex arctan, log, sin and cos, we get $z(t) = \frac{e \sin(2(et+g)) - f \sinh(2(ft+h))}{\cosh(2(ft+h)) + \cos(2(et+g))} + i \frac{f \sin(2(et+g)) + e \sinh(2(ft+h))}{\cosh(2(ft+h)) + \cos(2(et+g))}.$

Background	First ODE	Second ODE	PSM
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Zero Constant			



Background	Second ODE	PSM
Zero Constant		

Then
$$z(t) = x(t) + iy(t) = \frac{-\left(t + \frac{c}{c^2 + d^2}\right) - i\frac{d}{c^2 + d^2}}{\left(t + \frac{c}{c^2 + d^2}\right)^2 + \left(\frac{d}{c^2 + d^2}\right)^2}$$



Background	First ODE	Second ODE	PSM
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If we let
$$m = c/(c^2 + d^2)$$
 and $n = d/(c^2 + d^2)$ then
 $x(t) = -\frac{t+m}{(t+m)^2 + n^2}$ and $y(t) = -\frac{n}{(t+m)^2 + n^2}$.



Background	First ODE	Second ODE	PSM
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 $(x(t), y(t)) \rightarrow (0, 0)$ as $t \rightarrow \pm \infty$, so the solution starting from any point is on a homoclinic orbit, with the same homoclinic point.



Background	First ODE	Second ODE	PSM
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$$x^{2} + y^{2} = \frac{(t+m)^{2} + n^{2}}{((t+m)^{2} + n^{2})^{2}} = \frac{1}{(t+m)^{2} + n^{2}} = -\frac{y}{n},$$



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or
$$x^{2} + \left(y - \frac{1}{2n}\right) = \left(\frac{1}{2n}\right)^{2}.$$



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All homoclinic orbits are circles,
center and radius 1/(2n).



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First ODE 000€000000 Second ODE

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Background	First ODE	Second ODE	PSM
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Positive Real Constant

If
$$b = 0$$
 and $a > 0$, then $e = \sqrt{a}$, $f = 0$ and

$$z(t) = x(t) + iy(t) = \sqrt{a} \cdot \frac{\sin(2(\sqrt{at} + g)) + i\sinh(2h)}{\cosh(2h) + \cos(2(\sqrt{at} + g))}$$



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If b = 0 and a > 0, then $e = \sqrt{a}$, f = 0 and

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Orbits are circles $x^2 + (y - m)^2 = m^2 - a$ where $m = a \coth(2h)$, all of which are periodic, so no heteroclinic orbits.



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Orbits are circles $x^2 + (y - m)^2 = m^2 - a$ where $m = a \coth(2h)$, all of which are periodic, so no heteroclinic orbits. $z' = z^2 + 1$:





Positive Real (Constant Period		
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Background	First ODE	Second ODE	PSM

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Velocity small near the origin, can become very large away from the origin.



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so the period is the same on each circular orbit.

Velocity small near the origin, can become very large away from the origin. $\dot{z} = z^2 + 1$, z(0) = 0.05 + 0.05i:





Background	First ODE	Second ODE	PSM
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Negative Real Constant

If
$$b = 0$$
 and $a < 0$, then $\pm (e + if) = \sqrt{a} = i\sqrt{-a}$, so $e = 0$ and $f = \sqrt{-a}$, and

$$z(t) = x(t) = iy(t) = \sqrt{-a} \cdot \frac{-\sinh(2(\sqrt{-a}t+h)) + i\sin(2g)}{\cosh(2(\sqrt{-a}t+h)) + \cos(2g)}.$$



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As $t \to \pm \infty$, $z(t) \to \mp \sqrt{-a}$, every point lies on a heteroclinic orbit with limit points on the real axis.


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As $t \to \pm \infty$, $z(t) \to \pm \sqrt{-a}$, every point lies on a heteroclinic orbit with limit points on the real axis. Orbits are arcs of circles: $x^2 + (y - g)^2 = g^2 - a$ where $g = a \cot(2e)$.



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Background	First ODE	Second ODE	PSM

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Complex Constant			

If
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$$z(t) = \frac{e \sin(2(et+g)) - f \sinh(2(ft+h))}{\cosh(2(ft+h)) + \cos(2(et+g))} + i \frac{f \sin(2(et+g)) + e \sinh(2(ft+h))}{\cosh(2(ft+h)) + \cos(2(et+g))}.$$



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As $t \to \pm \infty$, $(x, y) \to \pm (-f, e)$, every point on the plane lies on a heteroclinic orbit.



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As $t \to \pm \infty$, $(x, y) \to \pm (-f, e)$, every point on the plane lies on a heteroclinic orbit.

Orbits cannot be represented as algebraic equations in x and y only, and are spirals similar to Carnu or Euler spirals, with exponential convergence for large magnitude t.

Background	First ODE	Second ODE	PSM
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First Example

$$\dot{z} = z^2 + (1+i), \ z(0) = -1, -0.8, \dots, 1.$$







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Same exponential convergence after more dramatic intermediate circular curve.



Second Example			
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$$\dot{z} = z^2 + 1 + i/2$$
, with $z(0) = 0, 0.1, 0.2, 0.3$.





Background	First ODE	Second ODE	PSM
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Second Example			

$$\dot{z} = z^2 + 1 + i/2$$
, with $z(0) = 0, 0.1, 0.2, 0.3$.



The smaller the ratio a/b, the faster the convergence of the spiral.



Background	First ODE	Second ODE	PSM
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Second ODF			

Consider
$$\dot{x} = -y(1 - ax - by)$$
 and $\dot{y} = x(1 - ax - by)$ with $x(0) = c, y(0) = d$.



Background	First ODE	Second ODE	PSM
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Second ODF			

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Background 000	First ODE	0000
Second ODE		

Consider
$$\dot{x} = -y(1 - ax - by)$$
 and $\dot{y} = x(1 - ax - by)$ with $x(0) = c$, $y(0) = d$.

Eliminating t,
$$\dot{y} = -y/x$$
, or $x^2 + y^2 = r^2$ where $c^2 + d^2 = r^2$.



Background 000	First ODE	0000
Second ODE		

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If $r < 1/(a^2 + b^2)$, orbits will be periodic. Otherwise, orbits are heteroclinic on arcs of circles, with endpoints on the line 1 - ax - by = 0.



Background 000	First ODE	0000
Second ODE		

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The line -ax - by = 0 could be called a heteroclinic line.

Background	First ODE	Second ODE	PSM
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Analytic Solution			

Starting with
$$\dot{x} = -y(1 - ax - by)$$
 and $\dot{y} = x(1 - ax - by)$ with $x(0) = c$, $y(0) = d$, let $r = \sqrt{c^2 + d^2}$, $x(t) = r\cos(\theta(t))$ and $y(t) = r\sin(\theta(t))$.



Background	First ODE	Second ODE	PSM
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Analytic Solution			

Starting with
$$\dot{x} = -y(1 - ax - by)$$
 and $\dot{y} = x(1 - ax - by)$ with $x(0) = c$, $y(0) = d$, let $r = \sqrt{c^2 + d^2}$, $x(t) = r \cos(\theta(t))$ and $y(t) = r \sin(\theta(t))$. Then $\dot{\theta} = 1 - ar \cos \theta - br \sin \theta$, which has solutions

$$\theta(t) = -2 \arctan\left(\frac{-br + \tanh\left(\frac{t+C}{2}\sqrt{r^2(a^2+b^2)-1}\right)\sqrt{r^2(a^2+b^2)-1}}{1+ar}\right)$$

when $r^2 > 1/(a^2 + b^2)$, and
 $\theta(t) = -2 \arctan\left(\frac{-br - \tan\left(\frac{t+C}{2}\sqrt{1-r^2(a^2+b^2)}\right)\sqrt{1-r^2(a^2+b^2)}}{1+ar}\right) + 2k\pi$
when $r^2 < 1/(a^2 + b^2)$, and k is an integer chosen to ensure $\theta(t)$
stays continuous and monotonic.

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Background	First ODE	Second ODE	PSM
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Example			

$$\dot{x} = -y(1 - x - y)$$
 and $\dot{y} = x(1 - x - y)$ with $d = 0$ and $c = 0.05, 0.1, 0.15, \dots, 2$:



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Background	First ODE	PSM

More General Case

 $\dot{x} = -yf(x, y)$, $\dot{y} = xf(x, y)$ for any function f(x, y) has arcs of circles as orbits, with the solutions of f(x, y) = 0 as heteroclinic lines.



Background	First ODE	Second ODE	PSM
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More General Case

 $\dot{x} = -yf(x, y)$, $\dot{y} = xf(x, y)$ for any function f(x, y) has arcs of circles as orbits, with the solutions of f(x, y) = 0 as heteroclinic lines.

For example, $x' = -y(y - x^2)$ and $y' = x(y - x^2)$ with x(0) = 0and $y(0) = -0.1, -0, 2, -0.3, \dots, -6$.





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Taylor methods to solve $\dot{y} = f(t, y)$ writes y(t + h) as a Taylor series around y(t), substituting successive derivatives of f.



Power Series Met	hod		
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BUT if the RHS of the ode is polynomial in the dependent variables, we can write out y as a power series in t, substitute, and explicitly find the coefficients – the Power Series Method.



Power Series N	lethod		
Background	First ODE	Second ODE	PSM
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BUT if the RHS of the ode is polynomial in the dependent variables, we can write out y as a power series in t, substitute, and explicitly find the coefficients – the Power Series Method. Usually only seen when solving linear second order odes with non constant coefficients (Frobenius around regular singular points).



Power Series N	lethod		
Background	First ODE	Second ODE	PSM
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Applying the PSM			
Background	First ODE	Second ODE	PSM
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Virtually every system of first order initial value odes can be systematically transformed into an equivalent polynomial form.



Applying the PSM			
ackground	First ODE	Second ODE	PSM
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Applying the PC	M		
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Background	First ODE	Second ODE	PSM

Advantages:

• Arbitrary order available, at any level at any time.



Applying the PC	M		
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Background	First ODE	Second ODE	PSM

- Arbitrary order available, at any level at any time.
- A priori error estimate available.



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Applying the P	SM		
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- Arbitrary order available, at any level at any time.
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- Solution curve available at every value of *t*, leading to a straightforward approach to delay difference equations.



Applying the P	SM		
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- Arbitrary order available, at any level at any time.
- A priori error estimate available.
- Machine precision possible effectively symplectic.
- Solution curve available at every value of *t*, leading to a straightforward approach to delay difference equations.
- No transcendental function evaluation, so is much faster.



Simple Examples			
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Background	First ODE	Second ODE	PSM

$$\dot{y} = \sin t$$
, $y(0) = a$.



Simple Examples			
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 $\dot{u}_1 = u_2$, $u_1(0) = a$; $\dot{u}_2 = u_3$, $u_2(0) = 0$; $\dot{u}_3 = -u_2$, $u_3(0) = 1$.



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$$\dot{y} = \sin y, \ y(0) = a.$$


Simple Examples			
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 $\dot{u}_1 = u_2$, $u_1(0) = a$; $\dot{u}_2 = (\cos y)\dot{y} = u_3u_2$, $u_2(0) = \sin(a)$;
 $\dot{u}_3 = (-\sin y)\dot{y} = -u_2^2$, $u_3(0) = \cos(a)$.



Arbitrary Power			
Background 000	First ODE	Second ODE	PSM 0000

$$\dot{y} = y^{\alpha}$$
, $y(0) = a$.

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$$\dot{y} = y^{lpha}$$
, $y(0) = a$. Let $u_1 = y$, $u_2 = y^{lpha}$, $u_3 = 1/y$.



Arbitrary Doword			
Background	First ODE	Second ODE	PSM

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$$\dot{y} = y^{lpha}$$
, $y(0) = a$. Let $u_1 = y$, $u_2 = y^{lpha}$, $u_3 = 1/y$. Then $\dot{u}_1 = u_2$, $u_1(0) = a$;



Arhitrary Powers			
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Background	First ODE	Second ODE	PSM

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 $u_1(0) = a$; $\dot{u}_2 = \alpha y^{\alpha - 1} \dot{y} = \alpha y^{2\alpha - 1} = \alpha u_2^2 u_3$, $u_2(0) = a^{\alpha}$;



Arbitrary Powers			
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 $\dot{u}_3 = (-1/y^2) \dot{y} = -u_3^2 u_2$, $u_3(0) = 1/a$.



Arhitrary Power	c .		
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Background	First ODE	Second ODE	PSM

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Better, let $u_4 = u_2 u_3 = y^{\alpha - 1}$.



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Better, let $u_4 = u_2u_3 = y^{\alpha-1}$. Then $\dot{u}_1 = u_2$, $\dot{u}_2 = \alpha u_2 u_4$, $\dot{u}_3 = -u_3 u_4$, only 3 Cauchy products.

Even better, let $u_1 = y$, $u_2 = y^{\alpha - 1}$.



Arhitrary Powers			
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Even better, let $u_1 = y$, $u_2 = y^{\alpha - 1}$. Then $\dot{u}_1 = u_1 u_2$, $u_1(0) = a^{\alpha}$; $\dot{u}_2 = (\alpha - 1)y^{\alpha - 2}y^{\alpha}$



Arbitrary Powers			
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Even better, let $u_1 = y$, $u_2 = y^{\alpha - 1}$. Then $\dot{u}_1 = u_1 u_2$, $u_1(0) = a^{\alpha}$; $\dot{u}_2 = (\alpha - 1)y^{\alpha - 2}y^{\alpha} = (\alpha - 1)y^{2\alpha - 2} = (\alpha - 1)u_2^2$, $u_2(0) = a^{\alpha - 1}$.



Arbitrary Powers			
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Better, let $u_4 = u_2 u_3 = y^{\alpha-1}$. Then $\dot{u}_1 = u_2$, $\dot{u}_2 = \alpha u_2 u_4$, $\dot{u}_3 = -u_3 u_4$, only 3 Cauchy products.

Even better, let $u_1 = y$, $u_2 = y^{\alpha-1}$. Then $\dot{u}_1 = u_1 u_2$, $u_1(0) = a^{\alpha}$; $\dot{u}_2 = (\alpha - 1)y^{\alpha-2}y^{\alpha} = (\alpha - 1)y^{2\alpha-2} = (\alpha - 1)u_2^2$, $u_2(0) = a^{\alpha-1}$. Only 2 Cauchy products.

