

238 Chapter 5 Test

April 16, 2013

Name: KEY

By printing my name I pledge to uphold the honor code.

1. Fill in the blank.

a) A function $T : V \rightarrow W$ between vector spaces V and W is a linear transformation if the

following two equations are satisfied: $T(u+v) = T(u) + T(v)$ holds for all

$u, v \in V$ and $T(c \cdot u) = c \cdot T(u)$ holds for all

$u \in V, c \in \mathbb{R}$.

b) A linear transformation $T : V \rightarrow W$ is completely determined by its value on

ANY BASIS FOR V .

c) Eigenvalues for a matrix A are found by computing

ROOTS of $\det(\lambda I - A)$

while eigenspaces are found by computing

$NS(\lambda I - A)$.

2. Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x - y + z \\ 3y \end{pmatrix}$.

a) Prove that T is a linear transformation using the definition.

$$T \begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \\ z_1 + z_2 \end{pmatrix} =$$

$$T \left(c \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right) = T \begin{pmatrix} cx \\ cy \\ cz \end{pmatrix} = \begin{pmatrix} cx - cy + cz \\ 3cy \end{pmatrix}$$

$$= c \begin{pmatrix} x - y + z \\ 3y \end{pmatrix}$$

$$= c T \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\text{vs. } T \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} + T \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} = \begin{pmatrix} x_1 - y_1 + z_1 \\ 3y_1 \end{pmatrix} + \begin{pmatrix} x_2 - y_2 + z_2 \\ 3y_2 \end{pmatrix}$$

$$= \begin{pmatrix} x_1 + x_2 - y_1 - y_2 + z_1 + z_2 \\ 3(y_1 + y_2) \end{pmatrix}$$

b) Let α be the standard basis for \mathbb{R}^3 and β be the standard basis for \mathbb{R}^2 . Find $[T]_{\alpha}^{\beta}$.

$$\begin{pmatrix} 1 & -1 & 1 \\ 0 & 3 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x - y + z \\ 3y \end{pmatrix}$$

3. Given $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 5 \end{pmatrix}$ and $T\begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} -3 \\ 1 \end{pmatrix}$

a) Given the matrix for T in terms of the standard basis.

$$\begin{pmatrix} 0 \\ 5 \end{pmatrix} = a \begin{pmatrix} 1 \\ 1 \end{pmatrix} + b \begin{pmatrix} -1 \\ 2 \end{pmatrix} \quad T\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{2}{3} T\begin{pmatrix} 1 \\ 1 \end{pmatrix} - \frac{1}{3} T\begin{pmatrix} -1 \\ 2 \end{pmatrix} = \frac{2}{3} \begin{pmatrix} 0 \\ 5 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} -3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$\begin{aligned} a-b &= 1 & 0 &= c \begin{pmatrix} 1 \\ 1 \end{pmatrix} + d \begin{pmatrix} -1 \\ 2 \end{pmatrix} \\ a+2b &= 0 & c-d &= 0 \end{aligned}$$

$$3a=2 \quad a=\frac{2}{3} \quad b=-\frac{1}{3} \quad c+d=1 \quad 3c=1 \quad c=\frac{1}{3} \quad d=\frac{2}{3}$$

$$T\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 0 \\ 5 \end{pmatrix} + \frac{1}{3} \begin{pmatrix} -3 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$[T] = \begin{pmatrix} 1 & -1 \\ 3 & 2 \end{pmatrix}$$

$$\begin{array}{ccc} \mathbb{R}^2 & \xrightarrow{P^{-1}} & \mathbb{R}^2 \\ \uparrow P & & \downarrow P^{-1} \\ \mathbb{R}^2 & \xrightarrow{[T]_\alpha} & \mathbb{R}^2 \end{array}$$

$$\begin{pmatrix} 0 & -3 \\ 5 & 1 \end{pmatrix} = [T]_\alpha$$

$$\begin{pmatrix} 0 & -3 \\ 5 & 1 \end{pmatrix} \begin{pmatrix} 2/3 & 1/3 \\ -1/3 & 1/3 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 3 & 2 \end{pmatrix}$$

b) Give a matrix $[T]_\beta^\beta$ such that $[T]_\beta^\beta$ is in Jordan canonical form for some basis β .

ie FIND ITS EIGENVALUES.

$$\det(\lambda I - \begin{pmatrix} 1 & -1 \\ 3 & 2 \end{pmatrix}) = \det \begin{pmatrix} \lambda-1 & 1 \\ -3 & \lambda-2 \end{pmatrix}$$

$$= (\lambda-1)(\lambda-2) + 3$$

$$= \lambda^2 - 3\lambda + 5$$

$$\lambda = \frac{3 \pm \sqrt{9-4 \cdot 5}}{2} = \frac{3 \pm \sqrt{-11}}{2} = \frac{3}{2} \pm \frac{\sqrt{11}}{2}i$$

$$[T]_\beta^\beta = \begin{pmatrix} \frac{3}{2} + \frac{\sqrt{11}}{2}i & 0 \\ 0 & \frac{3}{2} - \frac{\sqrt{11}}{2}i \end{pmatrix}$$

4. The characteristic polynomial of the matrix $A = \begin{pmatrix} 3 & 2 & 4 \\ 2 & 0 & 2 \\ 4 & 2 & 3 \end{pmatrix}$ is $(\lambda+1)^2(\lambda-8)$.

a) Compute all of the eigenspaces for the matrix A .

$$E_{-1} = \text{NS} \begin{pmatrix} -4 & -2 & -4 \\ -2 & -1 & -2 \\ -4 & -2 & -4 \end{pmatrix}$$

$$\begin{pmatrix} -5 & 2 & 4 \\ 2 & -8 & 2 \\ 4 & 2 & -5 \end{pmatrix}$$

$$E_{-1} = \left\{ \begin{pmatrix} -\frac{1}{2}c_2 - c_3 \\ c_2 \\ c_3 \end{pmatrix} \mid c_2, c_3 \in \mathbb{R} \right\}$$

$$E_8 = \text{NS} \begin{pmatrix} 5 & -2 & -4 \\ -2 & 8 & -2 \\ -4 & -2 & 5 \end{pmatrix}$$

$$\text{NS} \begin{pmatrix} 1 & 1/2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \left\{ \begin{pmatrix} -\frac{1}{2}c_2 - c_3 \\ c_2 \\ c_3 \end{pmatrix} \right\}$$

$$E_8 = \left\{ \begin{pmatrix} c_3 \\ \frac{1}{2}c_3 \\ c_3 \end{pmatrix} \mid c_3 \in \mathbb{R} \right\}$$

$$c_1 + \frac{1}{2}c_2 + c_3 = 0$$

$$c_2, c_3 \text{ free}$$

VAR

$$= \text{NS} \begin{pmatrix} 1 & -4 & 1 \\ 0 & -18 & -9 \\ 0 & -18 & 9 \end{pmatrix}$$

$$= \text{NS} \begin{pmatrix} 1 & -4 & 1 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \end{pmatrix} = \text{NS} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \end{pmatrix}$$

$$c_1 - c_3 = 0$$

$$c_2 - \frac{1}{2}c_3 = 0$$

b) Find P and D such that D is diagonal and $A = PDP^{-1}$.

$$\mathbb{R}^3 \xrightarrow{\begin{pmatrix} 3 & 2 & 4 \\ 2 & 0 & 2 \\ 4 & 2 & 3 \end{pmatrix}} \mathbb{R}^3$$

$$D = \begin{pmatrix} -1 & & \\ & -1 & \\ & & 8 \end{pmatrix}$$

$$\mathbb{R}^3 \xrightarrow{\begin{pmatrix} -1 & & \\ & -1 & \\ & & 8 \end{pmatrix}} \mathbb{R}^3$$

$$P = \begin{pmatrix} -1 & -1 & 2 \\ 2 & 0 & 1 \\ 0 & 1 & 2 \end{pmatrix}$$

$$\beta = \left\{ \begin{pmatrix} -1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \right\}$$

5. True/False, circle T or F as appropriate. If you have time after you have finished the rest of the exam you may go back and explain your answers for possible partial credit/extra credit. 20

a) ☒ T F If $T(0) \neq 0$, then T is not a linear transformation.

b) ☒ T F The definition of matrix multiplication from Chapter 1 comes from what we would need for composition of linear transformations to be multiplication of the corresponding matrices.

c) ☒ T F Every matrix has a unique Jordan canonical form (up to reordering the Jordan blocks).

d) ☒ T F A two by two matrix with repeated eigenvalues is either already diagonal or not diagonalizable.

e) ☒ T F $\begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$ is an eigenvector for $\begin{pmatrix} 1 & -1 & 2 & 1 \\ -6 & 9 & -1 & 1 \\ 1 & 2 & -3 & 3 \\ 4 & -2 & 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 3 \\ 3 \end{pmatrix}$

6. More fill in the blanks.

a) A matrix is diagonalizable if and only if

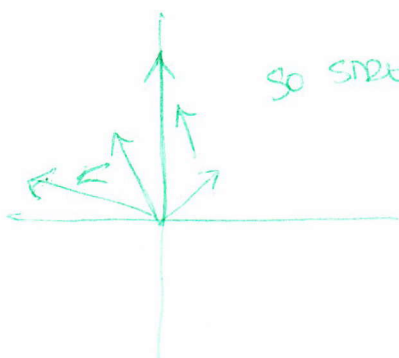
LOTS OF EIGENVALUES.

b) The dimension of the eigenspace $E_\lambda \leq$ MULTIPLICITY OF EIGENVALUE.

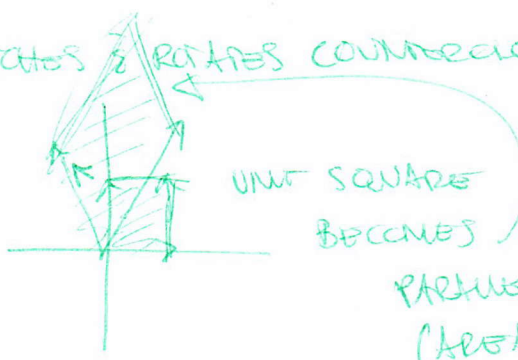
c) Describe one way the diagonal form of a matrix can be useful.

RAISING MATRICES TO LARGE POWERS

7. Describe the linear transformation from problem 3 in terms of what the transformation does to \mathbb{R}^2 .



SO STRETCHES & ROTATES COUNTERCLOCKWISE.



UNIT SQUARE BECOMES

PARALLELOGRAM.
(AREA 3)