

1. (1 pt) Library/FortLewis/DiffEq/3-Linear-systems/01-Intro-to-systems/KJ-4-1-13-multians.pg

Let

$$A(t) = \begin{bmatrix} \frac{2}{\sqrt{4-t}} & \ln(|t|) \\ & e^{3t} \end{bmatrix}.$$

(1) Find $A'(t)$.

$$A'(t) = \begin{bmatrix} \underline{\hspace{2cm}} & \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} & \underline{\hspace{2cm}} \end{bmatrix}$$

(2) Find $A''(t)$.

$$A''(t) = \begin{bmatrix} \underline{\hspace{2cm}} & \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} & \underline{\hspace{2cm}} \end{bmatrix}$$

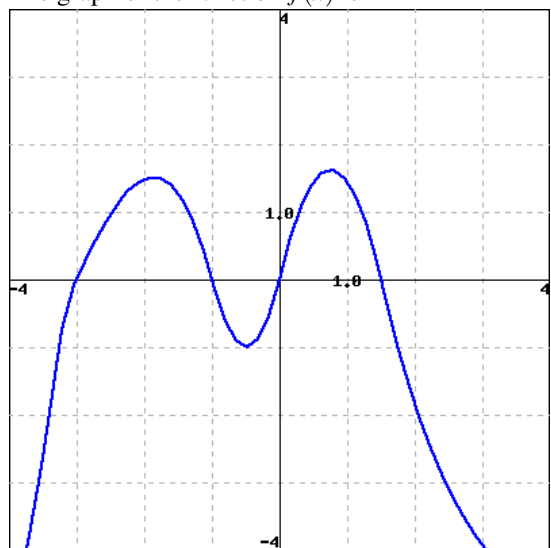
(3) $A(t)$ is defined for all t in the interval _____

$A'(t)$ is defined for all t in the interval _____

$A''(t)$ is defined for all t in the interval _____

2. (1 pt) Library/Rochester/setDiffEQ6AutonomousStability-/ur.de.6.1.pg

The graph of the function $f(x)$ is



(the horizontal axis is x.)

Consider the differential equation $x'(t) = f(x(t))$.

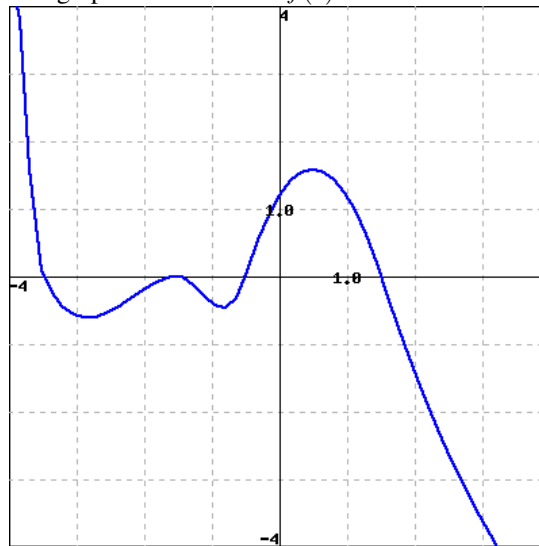
List the constant (or equilibrium) solutions to this differential

equation in increasing order and indicate whether or not these equations are stable, semi-stable, or unstable.

- _____ ?
- _____ ?
- _____ ?
- _____ ?

3. (1 pt) Library/Rochester/setDiffEQ6AutonomousStability-/ur.de.6.2.pg

The graph of the function $f(x)$ is



(the horizontal axis is x.)

Given the differential equation $x'(t) = f(x(t))$.

List the constant (or equilibrium) solutions to this differential equation in increasing order and indicate whether or not these equations are stable, semi-stable, or unstable.

- _____ ?
- _____ ?
- _____ ?
- _____ ?

4. (1 pt) Library/Rochester/setDiffEQ6AutonomousStability-/ur.de.6.3.pg

Given the differential equation $x' = -(x + 2.5) * (x + 0.5)^3 * (x - 1)^2 * (x - 2)$.

List the constant (or equilibrium) solutions to this differential equation in increasing order and indicate whether or not these equations are stable, semi-stable, or unstable. (It helps to **sketch the graph**. xFunctions will plot functions as well as phase planes.)

- _____ ?
- _____ ?

____ ?
____ ?

5. (1 pt) Library/Rochester/setDiffEQ6AutonomousStability-
/ur.de.6.4.pg

Given the differential equation $x'(t) = -x^4 + 3x^3 + 8x^2 - 12x - 16$.

List the constant (or equilibrium) solutions to this differential equation in increasing order and indicate whether or not these equations are stable, semi-stable, or unstable. (It helps to **sketch the graph**. xFunctions will plot functions as well as phase planes.)

____ ?
____ ?
____ ?
____ ?

6. (1 pt) Library/Rochester/setDiffEQ13Systems1stOrder-
/ur.de.13.1.pg

Write the given second order equation as its equivalent system of first order equations.

$$u'' + 8u' + 4u = 0$$

Use v to represent the "velocity function", i.e. $v = u'(t)$. Use v and u for the two functions, rather than $u(t)$ and $v(t)$. (The latter confuses webwork. Functions like $\sin(t)$ are ok.)

$$u' = \underline{\hspace{2cm}}$$
$$v' = \underline{\hspace{2cm}}$$

Now write the system using matrices:

$$\frac{d}{dt} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} _ & _ \\ _ & _ \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}.$$

7. (1 pt) Library/Rochester/setDiffEQ13Systems1stOrder-
/ur.de.13.9.pg

Consider the following model for the populations of rabbits and wolves (where R is the population of rabbits and W is the population of wolves).

$$\frac{dR}{dt} = 0.05R(1 - 0.00025R) - 0.000703125RW$$

$$\frac{dW}{dt} = -0.05W + 0.000125RW$$

Find all the equilibrium solutions:

(a) In the absence of wolves, the population of rabbits approaches _____.

(b) In the absence of rabbits, the population of wolves approaches _____.

(c) If both wolves and rabbits are present, their populations approach $r =$ _____ and $w =$ _____.

8. (1 pt) Library/Rochester/setDiffEQ13Systems1stOrder-
/ur.de.13.11.pg

Solve the system

$$\frac{dx}{dt} = \begin{bmatrix} 8 & -4 \\ 4 & -2 \end{bmatrix} x$$

with the initial value $x(0) = \begin{bmatrix} -11 \\ -10 \end{bmatrix}$.

$$x(t) = \begin{bmatrix} \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} \end{bmatrix}.$$

9. (1 pt) Library/Rochester/setDiffEQ13Systems1stOrder-
/ur.de.13.12.pg

Consider the interaction of two species of animals in a habitat. We are told that the change of the populations $x(t)$ and $y(t)$ can be modeled by the equations

$$\frac{dx}{dt} = 5x - 2y,$$

$$\frac{dy}{dt} = -2x + 2.5y.$$

? 1. What kind of interaction do we observe?

10. (1 pt) Library/Rochester/setDiffEQ13Systems1stOrder-
/ur.de.13.13.pg

Liam opens a bank account with an initial balance of 500 dollars. Let $b(t)$ be the balance in the account at time t . Thus $b(0) = 500$. The bank is paying interest at a continuous rate of 5% per year. Liam makes deposits into the account at a continuous rate of $s(t)$ dollars per year. Suppose that $s(0) = 500$ and that $s(t)$ is increasing at a continuous rate of 2% per year (Liam can save more as his income goes up over time).

(a) Set up a linear system of the form

$$\frac{db}{dt} = m_{11}b + m_{12}s,$$

$$\frac{ds}{dt} = m_{21}b + m_{22}s.$$

$$m_{11} = \underline{\hspace{1cm}},$$

$$m_{12} = \underline{\hspace{1cm}},$$

$$m_{21} = \underline{\hspace{1cm}},$$

$$m_{22} = \underline{\hspace{1cm}}.$$

(b) Find $b(t)$ and $s(t)$.

$$b(t) = \underline{\hspace{2cm}},$$

$$s(t) = \underline{\hspace{2cm}}.$$

11. (1 pt) Library/FortLewis/DiffEq/3-Linear-systems/07-Repeated-eigenvalues/KJ-4-7-29.pg

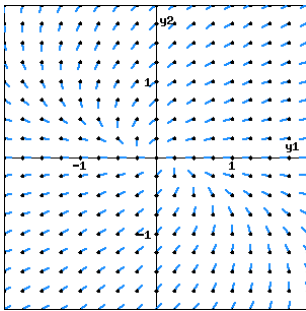
Match each linear system with one of the phase plane direction fields. (The blue lines are the arrow shafts, and the black dots are the arrow tips.)

?1. $y_1' = -y_1$
 $y_2' = 2y_1 - y_2$

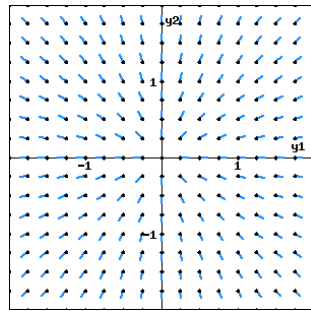
?2. $\vec{y}' = \frac{1}{2} \begin{bmatrix} -0.5 & 0 \\ 0 & -0.5 \end{bmatrix} \vec{y}$

?3. $y_1' = y_1 + y_2$
 $y_2' = y_2$

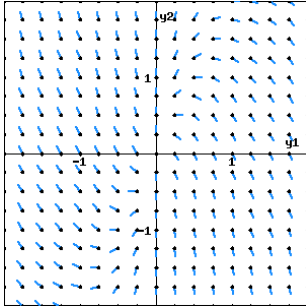
?4. $\vec{y}' = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \vec{y}$



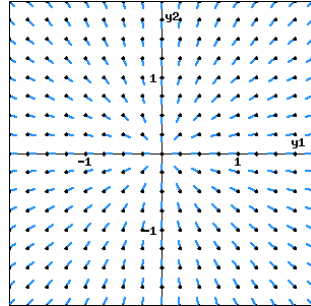
A



B



C



D

12. (1 pt) Library/FortLewis/DiffEq/3-Linear-systems/08-Complex-eigenvalues/KJ-4-6-04-multians.pg

Consider the linear system

$$\vec{y}' = \begin{bmatrix} 6 & 4 \\ -10 & -6 \end{bmatrix} \vec{y}.$$

Find the eigenvalues and eigenvectors for the coefficient matrix.

$$\lambda_1 = _, \vec{v}_1 = \begin{bmatrix} _ \\ _ \end{bmatrix}, \text{ and } \lambda_2 = _, \vec{v}_2 = \begin{bmatrix} _ \\ _ \end{bmatrix}$$

13. (1 pt) Library/FortLewis/DiffEq/3-Linear-systems/08-Complex-eigenvalues/KJ-4-6-13-multians.pg

Suppose A is a 2×2 real matrix with an eigenvalue $\lambda = 6i$ and corresponding eigenvector

$$\vec{v} = \begin{bmatrix} -1 - i \\ 1 \end{bmatrix}.$$

Determine a fundamental set (i.e., linearly independent set) of solutions for $\vec{y}' = A\vec{y}$, where the fundamental set consists entirely of *real* solutions.

Enter your solutions below. Use t as the independent variable in your answers.

$$\vec{y}_1(t) = \begin{bmatrix} _ \\ _ \\ _ \\ _ \end{bmatrix}$$

$$\vec{y}_2(t) = \begin{bmatrix} _ \\ _ \\ _ \\ _ \end{bmatrix}$$

14. (1 pt) Library/FortLewis/DiffEq/3-Linear-systems/08-Complex-eigenvalues/KJ-4-6-14-multians.pg

Suppose A is a 2×2 real matrix with an eigenvalue $\lambda = 1 + 5i$ and corresponding eigenvector

$$\vec{v} = \begin{bmatrix} -1 + i \\ i \end{bmatrix}.$$

Determine a fundamental set (i.e., linearly independent set) of solutions for $\vec{y}' = A\vec{y}$, where the fundamental set consists entirely of *real* solutions.

Enter your solutions below. Use t as the independent variable in your answers.

$$\vec{y}_1(t) = \begin{bmatrix} _ \\ _ \\ _ \\ _ \end{bmatrix}$$

$$\vec{y}_2(t) = \begin{bmatrix} _ \\ _ \\ _ \\ _ \end{bmatrix}$$

15. (1 pt) Library/FortLewis/DiffEq/3-Linear-systems/08-Complex-eigenvalues/KJ-4-6-20-multians.pg

Consider the linear system

$$\vec{y}' = \begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix} \vec{y}.$$

(1) Find the eigenvalues and eigenvectors for the coefficient matrix.

$$\lambda_1 = _, \vec{v}_1 = \begin{bmatrix} _ \\ _ \end{bmatrix}, \text{ and } \lambda_2 = _, \vec{v}_2 = \begin{bmatrix} _ \\ _ \end{bmatrix}$$

(2) Find the real-valued solution to the initial value problem

$$\begin{cases} y_1' = 3y_1 + 2y_2, & y_1(0) = 4, \\ y_2' = -5y_1 - 3y_2, & y_2(0) = -10. \end{cases}$$

Use t as the independent variable in your answers.

$$y_1(t) = \underline{\hspace{2cm}}$$

$$y_2(t) = \underline{\hspace{2cm}}$$

16. (1 pt) Library/FortLewis/DiffEq/3-Linear-systems/08-Complex-eigenvalues/KJ-4-6-32.pg

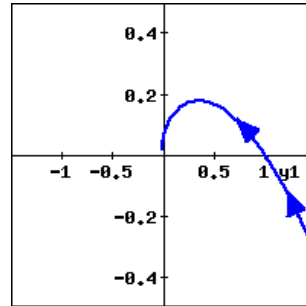
Match each initial value problem with the phase plane plot of its solution. (The arrows on the curves indicate how the solution point moves as t increases.)

1. $\vec{y}' = \begin{bmatrix} 1 & -0.5 \\ 0.5 & 1 \end{bmatrix} \vec{y}, \vec{y}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$

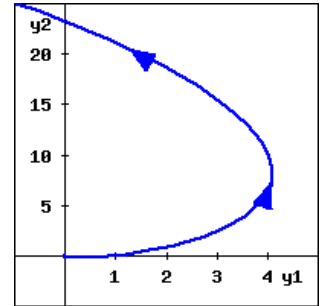
2. $\vec{y}' = \begin{bmatrix} -1 & -0.5 \\ 0.5 & -1 \end{bmatrix} \vec{y}, \vec{y}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$

3. $\vec{y}' = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \vec{y}, \vec{y}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$

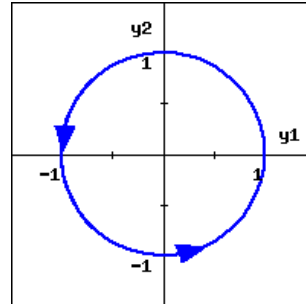
4. $\vec{y}' = \begin{bmatrix} 0 & 2 \\ -2 & 0 \end{bmatrix} \vec{y}, \vec{y}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$



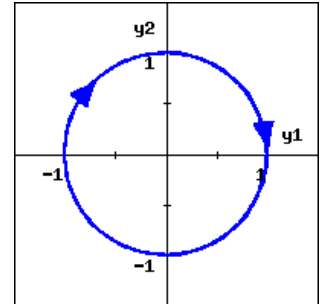
A



B



C



D