

Robot Design FIRST*LEGO*League Consolidated Award structure

Team Number Judging Room

Directions: For each skill area, clearly mark the box that best describes the team's accomplishments. If the team does not demonstrate skill in a particular area, then put an 'X' in the first box for Not Demonstrated (ND). Please provide as many written comments as you can to acknowledge each team's hard work and to help teams improve. When you have completed the evaluation, please circle the awards for which you would like this team to be considered.

> **Beginning Developing Accomplished Exemplary**

Di	Durability Evidence of structural integrity; ability to withstand rigors of competition							
N D	quite fragile; breaks a lot	frequent or significant faults/repairs	rare faults/repairs	sound construction; no repairs				
Mechanical Efficiency Economic use of parts and time; easy to repair and modify								
N D	excessive parts or time to repair/modify	inefficient parts or time to repair/modify	appropriate use of parts and time to repair/modify	streamlined use of parts and time to repair/modify				
Mechanization Ability of robot mechanisms to move or act with appropriate speed, strength and accuracy for intended tasks (propulsion and execution)								
N D	imbalance of speed, strength and accuracy on most tasks	imbalance of speed, strength and accuracy on some tasks	appropriate balance of speed, strength and accuracy on most tasks	appropriate balance of speed, strength and accuracy on every task				

Mechanical Design

Pr	Programming Quality Programs are appropriate for the intended purpose and would achieve consistent results, assuming no mechanical faults								
N D	would not achieve purpose AND would be inconsistent	would not achieve purpose OR would be inconsistent	should achieve purpose repeatedly	should achieve purpose every time					
Pr	Programming Efficiency Programs are modular, streamlined, and understandable								
N D	excessive code and difficult to understand	inefficient code and challenge to understand	appropriate code and easy to understand	streamlined code and easy for anyone to understand					
Automation/Navigation Ability of the robot to move or act as intended using mechanical and/or sensor feedback (with minimal reliance on driver intervention and/or program timing)									
N D	frequent driver intervention to aim AND retrieve robot	frequent driver intervention to aim OR retrieve robot	robot moves/acts as intended repeatedly w/ occasional driver intervention	robot moves/acts as intended every time with no driver intervention					

Comments:

Programming

De	Design Process Ability to develop and explain improvement cycles where alternatives are considered and narrowed, selections tested, designs improved (applies to programming as well as mechanical design)							
N D	organization AND explanation need improvement	organization OR explanation need improvement	systematic and well- explained	systematic, well-explained and well-documented				
Mission Strategy Ability to clearly define and describe the team's game strategy								
N D	no clear goals AND no clear strategy	no clear goals OR no clear strategy	clear strategy to accomplish the team's well defined goals	clear strategy to accomplish most/all game missions				
Innovation Creation of new, unique, or unexpected feature(s) (e.g. designs, programs, strategies or applications) that are beneficial in performing the specified tasks								
N D	original feature(s) with no added value or potential	original feature(s) with some added value or potential	original feature(s) with the potential to add significant	original feature(s) that add significant value				

Strategy & Innovation