

Robot Design FIRST*LEGO*League*Consolidated Award Structure

Team Number Judging Room

Directions: For each skill area, clearly mark the box that best describes the team's accomplishments. If the team does not demonstrate skill in a particular area, then put an 'X' in the first box for Not Demonstrated (ND). Please provide as many written comments as you can to acknowledge each team's hard work and to help teams improve. When you have completed the evaluation, please circle the awards for which you would like this team to be considered.

> **Beginning** Developing **Accomplished Exemplary**

| Di | Durability Evidence of structural integrity; ability to withstand rigors of competition | | | | | | | |
|--|--|---|---|---|--|--|--|--|
| N D | quite fragile; breaks a lot | frequent or significant faults/repairs | rare faults/repairs | sound construction; no repairs | | | | |
| M | Mechanical Efficiency Economic use of parts and time; easy to repair and modify | | | | | | | |
| N D | excessive parts or time to repair/modify | inefficient parts or time to repair/modify | appropriate use of parts and time to repair/modify | streamlined use of parts and time to repair/modify | | | | |
| Mechanization Ability of robot mechanisms to move or act with appropriate speed, strength and accuracy for intended tasks (propulsion and execution) | | | | | | | | |
| N D | imbalance of speed, strength and accuracy on most tasks | imbalance of speed, strength and accuracy on some tasks | appropriate balance of speed, strength and accuracy on most tasks | appropriate balance of speed, strength and accuracy on every task | | | | |

Mechanical Design

| P | Programming Quality Programs are appropriate for the intended purpose and would achieve consistent results, assuming no mechanical faults | | | | | | | |
|--|---|---|---|---|--|--|--|--|
| N D | 1 | would not achieve purpose OR would be inconsistent | should achieve purpose repeatedly | should achieve purpose every time | | | | |
| P | Programming Efficiency Programs are modular, streamlined, and understandable | | | | | | | |
| N D | | inefficient code and challenge to understand | appropriate code and easy to understand | streamlined code and easy for anyone to understand | | | | |
| Automation/Navigation Ability of the robot to move or act as intended using mechanical and/or sensor feedback (with minimal reliance on driver intervention and/or program timing) | | | | | | | | |
| N D | To aim AND retrieve robot | frequent driver intervention to aim OR retrieve robot | robot moves/acts as intended repeatedly w/ occasional driver intervention | robot moves/acts as intended every time with no driver intervention | | | | |

Comments:

Programming

| Design Process Ability to develop and explain improvement cycles where alternatives are considered and narrowed, selections tested, designs improved (applies to programming as well as mechanical design) | | | | | | | | |
|---|---|--|-----------------------------------|--|--|--|--|--|
| N D | organization AND explanation need improvement | organization OR explanation need improvement | systematic and well- explained | systematic, well-explained and well-documented | | | | |
| Mission Strategy Ability to clearly define and describe the team's game strategy | | | | | | | | |
| N | no clear goals AND no clear | no clear goals OR no clear | clear strategy to accomplish | clear strategy to accomplish | | | | |
| D | strategy | strategy | the team's well defined goals | most/all game missions | | | | |
| Innovation Creation of new, unique, or unexpected feature(s) (e.g. designs, programs, strategies or applications) that are beneficial in performing the specified tasks | | | | | | | | |
| N | original feature(s) with no | original feature(s) with some | original feature(s) with the | original feature(s) that add | | | | |
| D | added value or potential | added value or potential | potential to add significant | significant value | | | | |

Strategy & Innovation