

## Step 2

1. Open LME programming software
2. Save program as name of letter
3. Put a Motor Block on the Sequence Beam
4. Motors B \& C foward, $50 \%$ power, duration 1 sec .
5. Downloadgram to robot
6. Measure with a ruler and record the distance that the robot traveledin. per. sec.

Step 4

Observations and Limitations:
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