

Step 2

- 1. Open LME programming software
- 2. Save program as name of letter
- 3. Put a Motor Block on the Sequence Beam
- 4. Motors B & C foward, 50% power, duration 1 sec.
- 5. Downloadgram to robot
- 6. Measure with a ruler and record the distance that the robot traveled

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 in.	per.	sec.

Step 4

Robot Number:	Group:
Team Members:	

Step 1

- 1. Plot points on graph
- 2. Draw straight lines to all plotted points (must be in given order)
- Show on graph the path your robot will travel (≥, ≤ = good directional symbols)
- 4. Write the letter your path creates on the board

Step 3

Task List: (Steps needed to make the robot travel along plotted path)