

- 1. Open LME programming software
- 2. Save program as name of letter
- 3. Put a Motor Block on the Sequence Beam
- Motors B & C foward, 50% power, duration 1 sec.
- 5. Download program to robot
- 6. Measure with a ruler and record the distance that the robot traveled





Observations and Limitations:



- 1. Plot points on graph
- 2. Draw straight lines to all plotted points (must be in given order)
- Show on graph the path your robot will travel (≥, ≤ = good directional symbols)
- Write the letter your path creates on the board





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Robot Number: Team Members: Step

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