# Differential Equations <br> through the lens of power series 

Roger Thelwell

James Madison University
October 27, 2014

## Outline

(1) Introduction
(2) Example 1: $\frac{d y}{d x}=y$
(3) Example 2: $\frac{d}{d x} y=y(1-y)$
(4) Example 3: $\frac{d}{d x} y=\sin (y)$
(5) Example 4: $\frac{d}{d x} y=y \sin (y)$
(6) Theory
(7) Conclusion

## What are series?

If you have a sequence $\left\{a_{n}\right\}$, then add the terms:

$$
a_{0}+a_{1}+a_{2}+a_{3}+\ldots=\sum_{n=0}^{\infty} a_{n}
$$

Sometimes it converges, sometimes it doesn't. We are usually interested in the series that coverge.

## Examples

$$
\begin{aligned}
& \sum_{n=1}^{\infty} \frac{1}{n}=1+\frac{1}{2}+\frac{1}{3}+\ldots \\
& \sum_{n=1}^{\infty} \frac{1}{n^{2}}=1+\frac{1}{4}+\frac{1}{9}+\ldots \\
& \sum_{n=0}^{\infty} x^{n}=1+x^{1}+x^{2}+x^{3}+\ldots \\
& \sum_{n=0} a_{n} x^{n}=a_{0}+a_{1} x+a_{2} x^{2}+a_{3} x^{3}+\ldots \\
& \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^{n}=f(0)+\frac{f^{\prime}(0)}{1!} x+\frac{f^{\prime \prime}(0)}{2!} x^{2}+\frac{f^{(3)}(0)}{3!} x^{3}+\ldots
\end{aligned}
$$

## And more examples

And series for some common functions:

$$
\begin{gathered}
\exp (x)=\sum_{n=0}^{\infty} \frac{1}{n!} x^{n} \\
\sin (x)=\sum_{n=0}^{\infty} \frac{(-1)^{n}}{(2 n+1)!} x^{(2 n+1)} \\
\frac{1}{1-x}=\sum_{n=0}^{\infty} x^{n}
\end{gathered}
$$

## Example 1

## Consider

$$
\frac{d}{d x} y(x)=y(x) \quad y(0)=y_{0}
$$

## Phase Portrait

What do you think the solutions of

$$
\frac{d}{d x} y(x)=y(x) \quad y(0)=y_{0}
$$

to look like?
Let's use a phase portrait to get some intuition about typical solutions.

## An exact solution

We've got

$$
\frac{d y}{d x}=y
$$

Let's try to integrate it.

$$
\begin{aligned}
\frac{d y}{d x} & =y \\
\frac{1}{y} \frac{d y}{d x} & =1 \\
\int \frac{1}{y} \frac{d y}{d x} d x & =\int 1 d x \\
\int \frac{1}{y} d y & =\int 1 d x \\
\ln (y) & =x+C \quad \text { carefu!! } \\
\text { So } y(x) & =\exp (x+C)=K \exp (x) .
\end{aligned}
$$

## A power series solution?

How do we solve using power series?
Find coefficients $a_{n}$ so that

$$
y(x)=\sum_{n=0}^{\infty} a_{n} x^{n}=a_{0}+a_{1} x+a_{2} x^{2}+a_{3} x^{3}+\ldots
$$

to satisfy

$$
\frac{d}{d x} y(x)=y(x)
$$

## Power series

If

$$
y(x)=a_{0}+a_{1} x+a_{2} x^{2}+a_{3} x^{3}+\ldots=\sum_{n=0}^{\infty} a_{n} x^{n}
$$

then

$$
\begin{gathered}
\frac{d}{d x} y=a_{1}+2 a_{2} x+3 a_{3} x^{2}+\ldots=\sum_{n=0}^{\infty} ? ? ? x^{n} \\
\frac{d}{d x} y=a_{1}+2 a_{2} x+3 a_{3} x^{2}+\ldots=\sum_{n=0}^{\infty}(n+1) a_{n+1} x^{n}
\end{gathered}
$$

And substitute into

$$
\frac{d}{d x} y(x)=y(x)
$$

## Power series

We get

$$
\sum_{n=0}^{\infty}(n+1) a_{n+1} x^{n}=\sum_{n=0}^{\infty} a_{n} x^{n}
$$

If we compare coefficients for each power of $x$, we see

$$
(n+1) a_{n+1}=a_{n} \Longrightarrow a_{n+1}=\frac{1}{n+1} a_{n}
$$

So,

$$
\begin{aligned}
& a_{1}=\frac{1}{1} a_{0}=a_{0} \\
& a_{2}=\frac{1}{2} a_{1}=\frac{1}{2}\left(a_{0}\right)=\frac{a_{0}}{2!} \\
& a_{3}=\frac{1}{3} a_{2}=\frac{1}{3}\left(\frac{a_{0}}{2!}\right)=\frac{a_{0}}{3!}
\end{aligned}
$$

and ...

$$
a_{n}=\frac{1}{n!} a_{0}
$$

## Power series

Since

$$
a_{n}=\frac{1}{n!} a_{0},
$$

then

$$
\begin{gathered}
y(x)=\sum_{n=0}^{\infty} a_{n} x^{n}=\sum_{n=0}^{\infty} a_{0} \frac{1}{n!} x^{n}=? ? ? \\
y(x)=\sum_{n=0}^{\infty} a_{n} x^{n}=\sum_{n=0}^{\infty} a_{0} \frac{1}{n!} x^{n}=a_{0} \exp (x)
\end{gathered}
$$

Again using $y(x=0)=y_{0}$, we see that $a_{0}=y_{0}$, and recover the exact solution

$$
y(x)=y_{0} \exp (x)
$$

Usually, though, the function is harder identify.

## Example 2:

Now consider

$$
\frac{d}{d x} y=y(1-y)
$$

the logistic equation.

## Phase Portrait

What do you think solutions of

$$
\frac{d}{d x} y=y(1-y) \quad y(0)=y_{0}
$$

to look like?
Let's use a phase portrait again to get some intuition about typical solutions.

## Exact solution

Let's solve $\frac{d}{d x} y=y(1-y)$ by integrating directly.

$$
\begin{aligned}
\frac{d}{d x} y & =y(1-y) \\
\frac{1}{y(1-y)} \frac{d}{d x} y & =1 \\
\int \frac{1}{y(1-y)} d y & =\int 1 d y
\end{aligned}
$$

Lets solve $\frac{d}{d x} y=y(1-y)$ by integrating directly.

$$
\begin{aligned}
\frac{d}{d x} y & =y(1-y) \\
\frac{1}{y(1-y)} \frac{d}{d x} y & =1 \\
\int \frac{1}{y(1-y)} d y & =\int 1 d y
\end{aligned}
$$

## Power series

Let's now solve $\frac{d}{d x} y=y(1-y)$ using power series. Again, assume

$$
y(x)=\sum_{n=0}^{\infty} a_{n} x^{n} .
$$

Substituting,

$$
\sum_{n=0}^{\infty}(n+1) a_{n+1} x^{n}=\left(\sum_{n=0}^{\infty} a_{n} x^{n}\right) \cdot\left(1-\sum_{n=0}^{\infty} a_{n} x^{n}\right)
$$

## aside: Products

Power series are easy to add, subtract, differentiate and integrate - do it term by term.

If $A=\sum_{n=0} a_{n} x^{n}$ and $B=\sum_{n=0} b_{n} x^{n}$, what is $A \cdot B$ ?

$$
\begin{aligned}
\left(a_{0}+a_{1} x+\right. & \left.a_{2} x^{2}+a_{3} x^{3}+\ldots\right) \cdot\left(b_{0}+b_{1} x+b 2 x^{2}+b 3 x^{3}+\ldots\right) \\
= & \left(a_{0}+b_{0}\right)+\left(a_{0} b_{1}+a_{1} b_{0}\right) x+\left(a_{0} b_{2}+a_{1} b_{1}+a_{2} b_{0}\right) x^{2} \ldots \\
& \quad+\left(a_{0} b_{3}+a_{1} b_{2}+a_{2} b_{1}+a_{3} b_{0}\right) x^{3}+\ldots \\
=\sum_{n=0} & {\left[\sum_{i=0}^{n} a_{i} b_{n-i}\right] x^{n} }
\end{aligned}
$$

We'll call this the Cauchy Product

## aside: Matlab

```
In Matlab,
    \sum\mp@code{degree }}\mp@subsup{\sum}{n=0}{n}\mp@subsup{a}{i=0}{}\mp@subsup{b}{n-i}{
is
function cvec = cauchy_product(avec,bvec,degree)
for n = 1:degree + 1
    for i = 1:n
        j = n-i+1;
        cvec(n) = avec(i)*bvec(j)+cvec(n);
    end
end
```


## Power series

Back to it:

$$
\begin{aligned}
\sum_{n=0}^{\infty}(n+1) a_{n+1} x^{n} & =\left(\sum_{n=0}^{\infty} a_{n} x^{n}\right) \cdot\left(1-\sum_{n=0}^{\infty} a_{n} x^{n}\right) \\
& \left.=\sum_{n=0}^{\infty} a_{n} x^{n}-\sum_{n=0}^{\infty} \sum_{i=0}^{n} a_{i} a_{n-i} x^{n}\right) \\
& =\sum_{n=0}^{\infty}\left(a_{n}-c_{n}\right) x^{n}
\end{aligned}
$$

where $c_{n}$ is the result of the Cauchy product. We can again write a recursion relation:
or

$$
(n+1) a_{n+1}=a_{n}-\sum_{i=0}^{n} a_{i} a_{n-i}
$$

$$
a_{n+1}=\frac{1}{n+1}\left(a_{n}-\sum_{i=0}^{n} a_{i} a_{n-i}\right)
$$

## MATLAB solution

Matlab makes it easy. Since $a_{0}=y_{0}$, we need

$$
a_{n+1}=\frac{1}{n+1}\left(a_{n}-\sum_{i=0}^{n} a_{i} a_{n-i}\right)
$$

function $\mathrm{a}=$ solve_logistic(a0, degree)
for $\mathrm{n}=1$ : degree +1
$\mathrm{c}(\mathrm{n})=$ cauchy_product $(\mathrm{a}, \mathrm{a}, \mathrm{n})$;
$a(n+1)=1 /(n+1) *(a(n)-c(n))$;
end

## Example 3

Let's explore

$$
\frac{d}{d x} y=\sin (y)
$$

## Intuition

Consider

$$
\frac{d}{d x} y=\sin (y) \quad y(0)=y_{0}
$$

What do we expect?
Phase Portrait

## Exact solution

$$
\begin{aligned}
& \frac{d}{d x} y=\sin (y) \\
& \int \frac{1}{\sin (y)} d y=\int 1 d x
\end{aligned}
$$

These are getting a little tedious:
Wolfram Alpha says: $y(x)=2 \operatorname{arccot}(\exp (C-x))$

$$
\begin{aligned}
\frac{d}{d x} y & =\sin (y) \\
\int \frac{1}{\sin (y)} d y & =\int 1 d x \\
\int \frac{\sin (y)}{1-\cos ^{2}(y)} d y & =\int 1 d x \\
\int \frac{-1}{1-u^{2}} d u & =\int 1 d x \\
\int \frac{A}{1-u}+\frac{B}{1+u} d u & =\int 1 d x \\
1 / 2 \ln ((1-u) /(1+u)) & =x+C \\
\frac{1-\cos (y)}{1+\cos (y)} & =K \exp (2 x)
\end{aligned}
$$

## Power series

We have

$$
\frac{d}{d x} y=\sin (y) \quad y(0)=y_{0}
$$

We do have a series for $\sin (\bullet)$, but ...
Let's turn this into a polynomial system,
Let

$$
v_{1}(x)=y(x), \quad v_{2}(x)=\sin (y(x)), \quad \text { and } \quad v_{3}(x)=\cos (y(x))
$$

## The polynomial system

Taking $v_{1}(x)=y, \quad v_{2}(x)=\sin (y) \quad$ and $\quad v_{3}(x)=\cos (y)$, then

$$
\begin{array}{rlr}
v_{1}^{\prime} & =1 \cdot y^{\prime} \\
& =v_{2} & \\
v_{2}^{\prime} & =v_{3} \cdot y_{1}^{\prime}(0)=y_{0} \\
& =v_{2} v_{3} & \\
v_{2}(0)=\sin \left(y_{0}\right) \\
v_{3}^{\prime} & =-v_{2} \cdot y^{\prime} \\
& =-v_{2}^{2} & \\
v_{3}(0)=\cos \left(y_{0}\right)
\end{array}
$$

We can solve this system with series recursion, just as before.
Wwe can also consider the geometry....

## Geometry

Matlab allows us to see the structure.

## Decoupling

Since $v_{1}(x)=y, \quad v_{2}(x)=\sin (y) \quad$ and $\quad v_{3}(x)=\cos (y)$,

$$
\begin{aligned}
v_{1}^{\prime \prime}=y^{\prime} & =v_{2} v_{3} \\
v_{1}^{\prime \prime \prime}=\left(v_{2} v_{3}\right)^{\prime} & =v_{2} v_{3}^{\prime}+v_{2}^{\prime} v_{3} \\
& =v_{2}\left(-v_{2}\right)^{2}+\left(v_{2} v_{3}\right) v_{3} \\
& =-v_{2}^{3}+v_{2} v_{3}^{2} \\
& =-v_{2}^{3}+v_{2}\left(1-v_{2}^{2}\right) \\
& =-2\left(v_{2}\right)^{3}+v_{2}
\end{aligned}
$$

but $v_{2}=v_{1}^{\prime}=y^{\prime}$, and we've recast

$$
y^{\prime}=\sin (y) \quad \text { as } \quad y^{\prime \prime \prime}-y^{\prime}+2\left(y^{\prime}\right)^{3}=0
$$

Gröbner basis theory says this can always be done.

## Example 4

And one more to think about:

$$
\frac{d}{d x} y=y \sin (y)
$$

## Intuition?

$$
\frac{d}{d x} y=y \sin (y)
$$

## Analytic soln?

Maple
> dsolve(diff(y(x), $x)=y(x) * \sin (y(x))) ;$


## Analytic soln?

## Wolfram Alpha

Sample solution family:

(sampling $y(0)$ )

## Series?

Taking $v_{1}=y, v_{2}=y \sin (y), \quad v_{3}=? ? ? ?, v_{4}=? ? ? ?$,
Taking $v_{1}=y, v_{2}=y \sin (y), \quad v_{3}=\sin (y), v_{4}=\cos (y)$, then

$$
\begin{aligned}
v_{1}^{\prime} & =1 \cdot y^{\prime} & & \\
& =v_{2} & & v_{1}(0)=y_{0} \\
v_{2}^{\prime} & =(y \cos (y)+\sin (y)) \cdot y^{\prime} & & \\
& =\left(v_{1} v_{4}+v_{3}\right) v_{2} & & v_{2}(0)=y_{0} \sin \left(y_{0}\right) \\
v_{3}^{\prime} & =\cos (y) \cdot y^{\prime} & & \\
& =v_{2} v_{3} & & v_{3}(0)=\sin \left(y_{0}\right) \\
v_{4}^{\prime} & =-\sin (y) \cdot y^{\prime} & & \\
& =-v_{2}^{2} & & v_{4}(0)=\cos \left(y_{0}\right)
\end{aligned}
$$

Let $v_{5}=v_{1} v_{4}$ to reduce to a quadratic system.

## THEORY

We've been able to recast EVERY ODE that we've considered as a polynomial system.

U\$D 50 CASH PRIZE to the first person to send me an ODE with analytic solution that CAN'T be recast as a polynomial system.

## THEORY

Carothers et. al. 2005 [2]
Theorem
A function $v$ is the solution to an arbitrary component of a polynomial system of differential equations if and only if for some $n$ there is a polynomial $Q$ in $n+1$ variables so that $Q\left(v, v^{\prime}, \cdots, v^{(n)}\right)=0$.

This implies that the motion of our moon may be described without
reference to the earth, sun, or any other planets!

## THEORY

## Error Bound

Warne et. al. 2006 [3]
If we have (at $a=0$ ) a system $\mathbf{x}^{\prime}(t)=\mathbf{h}(\mathbf{x}(t)), \mathbf{x}(0)=\mathbf{b}$, then

$$
\begin{equation*}
\left\|\mathbf{x}(t)-\sum_{k=0}^{n} \mathbf{x}_{k} t^{k}\right\|_{\infty} \leq \frac{\|\mathbf{b}\|_{\infty}|K t|^{n+1}}{1-|M t|} \quad \text { for } \quad m \geq 2 \tag{1}
\end{equation*}
$$

Where the parameters K and M depend on immediately observable quantities of the original system;
$M$ is the largest row sum of coefficients, and $K=(m-1) c^{m-1}$, where $c=\max \left\{1,\|\mathbf{b}\|_{\infty}\right\}$ and $m=\operatorname{deg}(\mathbf{h})$.

## Conclusions

- Easily compute arbitrarily high order Taylor coefficients
- The tools can solve highly nonlinear and stiff problems
- Semi-analytic methods and
- interpolation free to machine capability (error and calculation)

Thanks to all the faculty and students of

and in particular to LTC Dr. Chalishajar.

## References

E. Fehlberg

Numerical integration of differential equations by power series expansions, illustrated by physical examples. Technical Report NASA-TN-D-2356, NASA, 1964.

固 David Carothers et. al.
Some properties of solutions to polynomial systems of differential equations.
Electronic Journal of Differential Equations, 2005:1-18, 2005.
围 P. G. Warne et. al.
Explicit a-priori error bounds and adaptive error control for approximation of nonlinear initial value differential systems.
Comput. Math. Appl., 52(12):1695-1710, 2006.

## For more information

- James Sochacki

Polynomial ordinary differential equations - examples, solutions, properties.
Neural Parallel \& Scientific Computations, 18(3-4):441-450, 2010.

