Differential Equations through the lens of power series

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October 27, 2014

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Outline



2 Example 1: $\frac{dy}{dx} = y$

3 Example 2:
$$\frac{d}{dx}y = y(1-y)$$

4 Example 3:
$$\frac{d}{dx}y = \sin(y)$$

5 Example 4:
$$\frac{d}{dx}y = y \sin(y)$$



Conclusion

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If you have a sequence $\{a_n\}$, then add the terms:

$$a_0+a_1+a_2+a_3+\ldots=\sum_{n=0}^\infty a_n$$

Sometimes it converges, sometimes it doesn't. We are usually interested in the series that coverge.

Examples

$$\sum_{n=1}^{\infty} \frac{1}{n} = 1 + \frac{1}{2} + \frac{1}{3} + \dots$$

$$\sum_{n=1}^{\infty} \frac{1}{n^2} = 1 + \frac{1}{4} + \frac{1}{9} + \dots$$

$$\sum_{n=0}^{\infty} x^n = 1 + x^1 + x^2 + x^3 + \dots$$

$$\sum_{n=0}^{\infty} a_n x^n = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$$

$$\sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n = f(0) + \frac{f'(0)}{1!} x + \frac{f''(0)}{2!} x^2 + \frac{f^{(3)}(0)}{3!} x^3 + \dots$$

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And more examples

And series for some common functions:

$$\exp(x) = \sum_{n=0}^{\infty} \frac{1}{n!} x^n$$

$$\sin(x) = \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n+1)!} x^{(2n+1)}$$
$$\frac{1}{1-x} = \sum_{n=0}^{\infty} x^n$$

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Example 1

Consider

$$\frac{d}{dx}y(x) = y(x) \quad y(0) = y_0$$

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What do you think the solutions of

$$\frac{d}{dx}y(x) = y(x) \quad y(0) = y_0$$

to look like?

Let's use a phase portrait to get some intuition about typical solutions.

An exact solution

We've got

$$\frac{dy}{dx} = y$$

Let's try to integrate it.

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An exact solution We've got

$$\frac{dy}{dx} = y$$

$$\frac{1}{y}\frac{dy}{dx} = 1$$

$$\int \frac{1}{y}\frac{dy}{dx} dx = \int 1 dx$$

$$\int \frac{1}{y} dy = \int 1 dx$$

$$\ln(y) = x + C \quad careful!$$
So $y(x) = \exp(x + C) = K \exp(x)$.

Using the initial condition $y(x = 0) = y_0$, we have

$$y(x) = y_0 \exp(x) = y_0 e^x$$

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A power series solution?

How do we solve using power series? Find coefficients a_n so that

$$y(x) = \sum_{n=0}^{\infty} a_n x^n = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$$

to satisfy

$$\frac{d}{dx}y(x)=y(x)$$

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$$y(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + \ldots = \sum_{n=0}^{\infty} a_nx^n$$

then

$$\frac{d}{dx}y = a_1 + 2a_2x + 3a_3x^2 + \ldots = \sum_{n=0}^{\infty} ???x^n$$

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$$y(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + \ldots = \sum_{n=0}^{\infty} a_nx^n,$$

then

$$\frac{d}{dx}y = a_1 + 2a_2x + 3a_3x^2 + \ldots = \sum_{n=0}^{\infty} (n+1)a_{n+1}x^n$$

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$$y(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + \ldots = \sum_{n=0}^{\infty} a_nx^n,$$

then

$$\frac{d}{dx}y = a_1 + 2a_2x + 3a_3x^2 + \ldots = \sum_{n=0}^{\infty} (n+1)a_{n+1}x^n$$

And substitute into

$$\frac{d}{dx}y(x)=y(x)$$

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Power series We get

$$\sum_{n=0}^{\infty} (n+1)a_{n+1}x^n = \sum_{n=0}^{\infty} a_n x^n$$

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We get

$$\sum_{n=0}^{\infty} (n+1)a_{n+1}x^n = \sum_{n=0}^{\infty} a_n x^n$$

If we compare coefficients for each power of x, we see

$$(n+1)a_{n+1} = a_n \implies a_{n+1} = \frac{1}{n+1}a_n$$

So.

$$a_{1} = \frac{1}{1}a_{0} = a_{0}$$

$$a_{2} = \frac{1}{2}a_{1} = \frac{1}{2}(a_{0}) = \frac{a_{0}}{2!}$$

$$a_{3} = \frac{1}{3}a_{2} = \frac{1}{3}\left(\frac{a_{0}}{2!}\right) = \frac{a_{0}}{3!}$$

and ...

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We get

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and ...

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Since

$$a_n=\frac{1}{n!}a_0,$$

then

$$y(x) = \sum_{n=0}^{\infty} a_n x^n = \sum_{n=0}^{\infty} a_0 \frac{1}{n!} x^n = ???$$

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Since

$$a_n=\frac{1}{n!}a_0,$$

then

$$y(x) = \sum_{n=0}^{\infty} a_n x^n = \sum_{n=0}^{\infty} a_0 \frac{1}{n!} x^n = a_0 \exp(x)$$

Again using $y(x = 0) = y_0$, we see that $a_0 = y_0$, and recover the exact solution

$$y(x) = y_0 \exp(x)$$

Usually, though, the function is harder identify.

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Example 2:

Now consider

$$\frac{d}{dx}y=y(1-y),$$

the logistic equation.

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What do you think solutions of

$$\frac{d}{dx}y = y(1-y) \quad y(0) = y_0$$

to look like?

Let's use a phase portrait again to get some intuition about typical solutions.

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Let's solve $\frac{d}{dx}y = y(1-y)$ by integrating directly.

$$\frac{d}{dx}y = y(1-y)$$
$$\frac{1}{y(1-y)}\frac{d}{dx}y = 1$$
$$\int \frac{1}{y(1-y)} dy = \int 1 dy$$

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$$\int \frac{A}{y} + \frac{B}{1-y} dy = \int 1 dy$$

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Lets solve $\frac{d}{dx}y = y(1-y)$ by integrating directly.

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$$\int \frac{1}{y} + \frac{1}{1-y}dy = \int 1 dy$$

$$\ln(y) - \ln(1-y) = x + C,$$
so $\frac{y}{1-y} = \exp(x+C) = K \exp(x)$

$$y(x) = \frac{1}{1+K}\exp(-x) \text{ with } K = \frac{y_0}{1-y_0}$$

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Let's now solve $\frac{d}{dx}y = y(1-y)$ using power series. Again, assume

$$y(x)=\sum_{n=0}^{\infty}a_nx^n.$$

Substituting,

$$\sum_{n=0}^{\infty} (n+1)a_{n+1}x^n = \left(\sum_{n=0}^{\infty} a_n x^n\right) \cdot \left(1 - \sum_{n=0}^{\infty} a_n x^n\right)$$

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aside: Products

Power series are easy to add, subtract, differentiate and integrate - do it term by term.

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aside: Products

Power series are easy to add, subtract, differentiate and integrate - do it term by term.

If
$$A = \sum_{n=0}^{\infty} a_n x^n$$
 and $B = \sum_{n=0}^{\infty} b_n x^n$, what is $A \cdot B$?

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aside: Products

Power series are easy to add, subtract, differentiate and integrate - do it term by term.

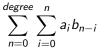
If
$$A = \sum_{n=0}^{n} a_n x^n$$
 and $B = \sum_{n=0}^{n} b_n x^n$, what is $A \cdot B$?
 $(a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots) \cdot (b_0 + b_1 x + b_2 x^2 + b_3 x^3 + \dots)$
 $= (a_0 + b_0) + (a_0 b_1 + a_1 b_0) x + (a_0 b_2 + a_1 b_1 + a_2 b_0) x^2 \dots$
 $+ (a_0 b_3 + a_1 b_2 + a_2 b_1 + a_3 b_0) x^3 + \dots$
 $= \sum_{n=0}^{n} \sum_{i=0}^{n} a_i b_{n-i} x^n$

We'll call this the Cauchy Product

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aside: MATLAB

In Matlab,



is

function cvec = cauchy_product(avec,bvec,degree)

```
for n = 1:degree + 1
    for i = 1:n
        j = n-i+1;
        cvec(n) = avec(i)*bvec(j)+cvec(n);
    end
end
```

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Back to it:

$$\sum_{n=0}^{\infty} (n+1)a_{n+1}x^n = \left(\sum_{n=0}^{\infty} a_n x^n\right) \cdot \left(1 - \sum_{n=0}^{\infty} a_n x^n\right)$$
$$= \sum_{n=0}^{\infty} a_n x^n - \sum_{n=0}^{\infty} \sum_{i=0}^{n} a_i a_{n-i} x^n$$
$$= \sum_{n=0}^{\infty} (a_n - c_n) x^n$$

where c_n is the result of the Cauchy product.

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Back to it:

$$\sum_{n=0}^{\infty} (n+1)a_{n+1}x^n = \left(\sum_{n=0}^{\infty} a_n x^n\right) \cdot \left(1 - \sum_{n=0}^{\infty} a_n x^n\right)$$
$$= \sum_{n=0}^{\infty} a_n x^n - \sum_{n=0}^{\infty} \sum_{i=0}^{n} a_i a_{n-i} x^n$$
$$= \sum_{n=0}^{\infty} (a_n - c_n) x^n$$

where c_n is the result of the Cauchy product. We can again write a recursion relation:

$$(n+1)a_{n+1} = a_n - \sum_{i=0}^n a_i a_{n-i}$$

or

$$a_{n+1} = \frac{1}{n+1} \left(a_n - \sum_{i=0}^n a_i a_{n-i} \right)$$

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Matlab solution

MATLAB makes it easy. Since $a_0 = y_0$, we need

$$a_{n+1} = \frac{1}{n+1} \left(a_n - \sum_{i=0}^n a_i a_{n-i} \right)$$

function a = solve_logistic(a0,degree)

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Example 3

Let's explore

$$\frac{d}{dx}y = \sin(y)$$

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Intuition

Consider

$$\frac{d}{dx}y = \sin(y) \quad y(0) = y_0$$

What do we expect? Phase Portrait

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$$\frac{d}{dx}y = \sin(y)$$
$$\int \frac{1}{\sin(y)} \, dy = \int 1 \, dx$$

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$$\frac{d}{dx}y = \sin(y)$$
$$\int \frac{1}{\sin(y)} \, dy = \int 1 \, dx$$

These are getting a little tedious: WOLFRAM ALPHA says: $y(x) = 2 \operatorname{arccot}(\exp(C-x))$

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ok...

$$\frac{d}{dx}y = \sin(y)$$

$$\int \frac{1}{\sin(y)} \, dy = \int 1 \, dx$$

$$\int \frac{\sin(y)}{1 - \cos^2(y)} \, dy = \int 1 \, dx$$

$$\int \frac{-1}{1 - u^2} \, du = \int 1 \, dx$$

$$\int \frac{A}{1 - u} + \frac{B}{1 + u} \, du = \int 1 \, dx$$

$$1/2 \ln((1 - u)/(1 + u)) = x + C$$

$$\frac{1 - \cos(y)}{1 + \cos(y)} = K \exp(2x)$$

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Power series

We have

$$\frac{d}{dx}y = \sin(y) \quad y(0) = y_0$$

We do have a series for $sin(\bullet)$, but ... Let's turn this into a polynomial system, Let

$$v_1(x) = y(x), \quad v_2(x) = \sin(y(x)), \text{ and } v_3(x) = \cos(y(x))$$

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The polynomial system

Taking $v_1(x) = y$, $v_2(x) = \sin(y)$ and $v_3(x) = \cos(y)$, then

$$v'_{1} = 1 \cdot y'$$

= v_{2} $v_{1}(0) = y_{0}$
 $v'_{2} = v_{3} \cdot y'$
= $v_{2} v_{3}$ $v_{2}(0) = \sin(y_{0})$
 $v'_{3} = -v_{2} \cdot y'$
= $-v_{2}^{2}$ $v_{3}(0) = \cos(y_{0})$

We can solve this system with series recursion, just as before.

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The polynomial system

Taking $v_1(x) = y$, $v_2(x) = \sin(y)$ and $v_3(x) = \cos(y)$, then

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 $v'_{3} = -v_{2} \cdot y'$
= $-v_{2}^{2}$ $v_{3}(0) = \cos(y_{0})$

We can solve this system with series recursion, just as before. Wwe can also consider the geometry....

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 Matlab allows us to see the structure.

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Decoupling

Since $v_1(x) = y$, $v_2(x) = \sin(y)$ and $v_3(x) = \cos(y)$,

$$v_1'' = y' = v_2 v_3$$

$$v_1''' = (v_2 v_3)' = v_2 v_3' + v_2' v_3$$

$$= v_2 (-v_2)^2 + (v_2 v_3) v_3$$

$$= -v_2^3 + v_2 v_3^2$$

$$= -v_2^3 + v_2 (1 - v_2^2)$$

$$= -2(v_2)^3 + v_2$$

but $v_2 = v'_1 = y'$, and we've recast

$$y' = \sin(y)$$
 as $y''' - y' + 2(y')^3 = 0$

Gröbner basis theory says this can always be done.

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Example 4

And one more to think about:

$$\frac{d}{dx}y = y\sin(y)$$

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Intuition?

$$\frac{d}{dx}y = y\sin(y)$$

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Analytic soln?

MAPLE

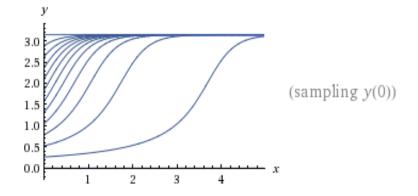
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Analytic soln?

Wolfram Alpha

Sample solution family:



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Series?

Taking
$$v_1 = y, v_2 = y \sin(y), v_3 = ????, v_4 = ????,$$

then

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Series?

Taking
$$v_1 = y, v_2 = y \sin(y), v_3 = \sin(y), v_4 = \cos(y)$$
, then

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Series?

Taking
$$v_1 = y, v_2 = y \sin(y), v_3 = \sin(y), v_4 = \cos(y)$$
, then
 $v'_1 = 1 \cdot y'$
 $= v_2 v_1(0) = y_0$
 $v'_2 = (y \cos(y) + \sin(y)) \cdot y'$
 $= (v_1 v_4 + v_3) v_2 v_2(0) = y_0 \sin(y_0)$
 $v'_3 = \cos(y) \cdot y'$
 $= v_2 v_3 v_3(0) = \sin(y_0)$
 $v'_4 = -\sin(y) \cdot y'$
 $= -v_2^2 v_4(0) = \cos(y_0)$

Let $v_5 = v_1 v_4$ to reduce to a quadratic system.

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THEORY

We've been able to recast EVERY ODE that we've considered as a polynomial system.

U\$D 50 CASH PRIZE to the first person to send me an ODE with analytic solution that **CAN'T** be recast as a polynomial system.

THEORY

Carothers et. al. 2005 [2]

Theorem

A function v is the solution to an arbitrary component of a polynomial system of differential equations if and only if for some n there is a polynomial Q in n + 1 variables so that $Q(v, v', \dots, v^{(n)}) = 0$.

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THEORY

Carothers et. al. 2005 [2]

Theorem

A function v is the solution to an arbitrary component of a polynomial system of differential equations if and only if for some n there is a polynomial Q in n + 1 variables so that $Q(v, v', \dots, v^{(n)}) = 0$.

This implies that the motion of our moon may be described without reference to the earth, sun, or any other planets!

THEORY Error Bound

Warne et. al. 2006 [3]

If we have (at a = 0) a system $\mathbf{x}'(t) = \mathbf{h}(\mathbf{x}(t)), \ \mathbf{x}(0) = \mathbf{b}$, then

$$\left\|\mathbf{x}(t) - \sum_{k=0}^{n} \mathbf{x}_{k} t^{k}\right\|_{\infty} \leq \frac{\left\|\mathbf{b}\right\|_{\infty} \left|Kt\right|^{n+1}}{1 - \left|Mt\right|} \quad \text{for} \quad m \geq 2$$
(1)

Where the parameters K and M depend on immediately observable quantities of the original system;

M is the largest row sum of coefficients, and $K = (m-1)c^{m-1}$, where $c = \max\{1, ||\mathbf{b}||_{\infty}\}$ and $m = deg(\mathbf{h})$.

• Easily compute arbitrarily high order Taylor coefficients

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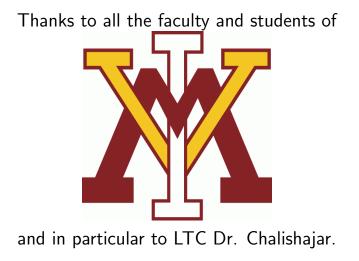
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- Easily compute arbitrarily high order Taylor coefficients
- The tools can solve highly nonlinear and stiff problems

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- The tools can solve highly nonlinear and stiff problems
- Semi-analytic methods and

- Easily compute arbitrarily high order Taylor coefficients
- The tools can solve highly nonlinear and stiff problems
- Semi-analytic methods and
- interpolation free to machine capability (error and calculation)



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For more information



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