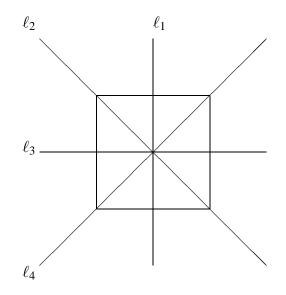
## VanWyk's 103

## **Section 4.5 Homework Problems**

1. The symmetry group of the square is  $D_4 = \{I, S, S^2, S^3, R_1, R_2, R_3, R_4\}$ , where each reflection  $R_i$  is about the line  $\ell_i$  below, and  $S = R_1R_2$ .



- (a) How many degrees does  $S = R_1R_2$  rotate the square counterclockwise? How about  $R_1R_3$ ?  $R_1R_4$ ?  $R_2R_1$ ?
- (b) Which elements of  $D_4$  are direct? Opposite?
- (c) Make a "multiplication table" for the elements of  $D_4$ , i.e., fill in the following chart. You can use the fact (which we will see later) that every element of  $D_4$  has to occur exactly once in each row and in each column. It might help to use a square card with numbers in each corner.

	Ι	S	$S^2$	$S^3$	$R_1$	$R_2$	$R_3$	$R_4$
Ι	Ι	S	$S^2$	$S^3$	$R_1$	$R_2$	$R_3$	$R_4$
S	S							
$S^2$	$S^2$							
$S^3$	$S^3$					$\frac{R_2}{R_2}$		
$R_1$	$R_1$				Ι			
$R_2$	$R_2$					Ι		
$R_3$	$R_3$						Ι	
$R_2$ $R_3$ $R_4$	$R_4$							Ι

- 2. In  $D_{231}$ , if you have the product  $R_{45}S^{199}R_{19}R_{71}S^{22}$ , is it some  $S^i$  or some  $R_i$ , and why?
- 3. In  $D_{180}$ , what is the angle between  $\ell_1$  and  $\ell_2$ ? What is the angle of minimal counterclockwise rotation (i.e., the angle of *S*)?

## VanWyk's 103

## **Section 4.5 Homework Answers**

1a. *S* rotates the square 90° counterclockwise, since the angle between  $\ell_1$  and  $\ell_2$  is 45°.  $R_1R_3$  rotates the square  $2 \cdot 90^\circ = 180^\circ$  counterclockwise.  $R_1R_4$  rotates the square  $2 \cdot 135^\circ = 270^\circ$  counterclockwise.  $R_2R_1$  rotates the square 90° *clockwise*, which is the same as 270° counterclockwise. 1b. The *S*<sup>*i*</sup>'s are always direct since they are rotations and the  $R_i$ 's are always opposite, since they are reflections. 1c.

	Ι	S	$S^2$	$S^3$	$R_1$	$R_2$	$R_3$	$R_4$
Ι	Ι	S	$S^2$	$S^3$	$R_1$	$R_2$	$R_3$	$R_4$
S	S	$S^2$	$S^3$	Ι	$R_4$	$R_1$	$R_2$	$R_3$
$S^2$	$S^2$	$S^3$	Ι	S	$R_3$	$R_4$	$R_1$	$R_2$
$S^3$	$S^3$	Ι	S	$ \frac{S^3}{I} \\ \frac{S}{S^2} $	$R_2$	$R_3$	$R_4$	$R_1$
$R_1$	$R_1$	$R_2$	$R_3$	$R_4$	Ι	S	$S^2$	$S^3$
$R_2$	$R_2$	$R_3$	$R_4$	$R_1$	$S^3$	Ι	S	$S^2$
$R_3$	$R_3$	$R_4$	$R_1$	$R_2$	$S^2$	$S^3$	Ι	S
$R_4$	$R_4$	$R_1$	$R_2$	$R_4$ $R_1$ $R_2$ $R_3$	S	$S^2$	$S^3$	Ι

Notice that this table illustrates how direct and opposite motions multiply:

$$\begin{array}{c|c}
D & O \\
\hline
D & D & O \\
\hline
O & O & D
\end{array}$$

2. It's some  $R_i$  because the product contains an odd number of opposite motions (so it must be opposite).

3. The angle between  $\ell_1$  and  $\ell_2$  in  $D_{180}$  is  $\frac{180^{\circ}}{180} = 1^{\circ}$ . So, the angle of rotation of  $S = R_1 R_2$  is  $2^{\circ}$ .